

OSTEP Chapter 28

ECE 3600, Fall 2022

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1. Locks

mutex = mutual exclusion, only one thread can hold the lock at any time

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;  
...  
Pthread_mutex_lock(&lock); // wrapper; exits on failure  
balance = balance + 1;  
Pthread_mutex_unlock(&lock);
```

How to implement?

Issues: Correctness (even on multiprocessors), Performance (time overhead), Fairness (no starve)

2. Simple Flag

```
1  typedef struct __lock_t { int flag; } lock_t;
2
3  void init(lock_t *mutex) {
4      // 0 -> lock is available, 1 -> held
5      mutex->flag = 0;
6  }
7
8  void lock(lock_t *mutex) {
9      while (mutex->flag == 1) // TEST the flag
10         ; // spin-wait (do nothing)
11     mutex->flag = 1;           // now SET it!
12 }
13
14 void unlock(lock_t *mutex) {
15     mutex->flag = 0;
16 }
```

Figure 28.1: First Attempt: A Simple Flag

Correct: no

Assume flag=0 to begin:

Thread 1	Thread 2
call lock()	
while (flag == 1)	
interrupt: switch to Thread 2	
	call lock()
	while (flag == 1)
	flag = 1;
	interrupt: switch to Thread 1
	flag = 1; // set flag to 1 (too!)

Figure 28.2: Trace: No Mutual Exclusion

3. Test-and-Set

Hardware test-and-set instruction (atomic exchange):

```
int TestAndSet(int *ptr, int new);
```

returns the old value and simultaneously updates to the new value.

```
1  typedef struct __lock_t {
2      int flag;
3  } lock_t;
4
5  void init(lock_t *lock) {
6      // 0: lock is available, 1: lock is held
7      lock->flag = 0;
8  }
9
10 void lock(lock_t *lock) {
11     while (TestAndSet(&lock->flag, 1) == 1)
12         ; // spin-wait (do nothing)
13 }
14
15 void unlock(lock_t *lock) {
16     lock->flag = 0;
17 }
```

Figure 28.3: A Simple Spin Lock Using Test-and-set

Correct: yes; Performance: bad (spinning); Fairness: no

Fix performance --> yield; Fix fairness --> queue

4. Other Hardware Primitives

Compare-and-swap:

```
int CompareAndSwap(int *ptr, int expected, int new);
```

returns the old value and simultaneously updates to the new value if old == expected.

Fetch-and-add:

```
int FetchAndAdd(int *ptr);
```

returns the old value and simultaneously adds 1 and stores the new value.

Can be used to implement ticket lock and ensure fairness.

```
1  typedef struct __lock_t {
2      int ticket;
3      int turn;
4  } lock_t;
5
6  void lock_init(lock_t *lock) {
7      lock->ticket = 0;
8      lock->turn   = 0;
9  }
10
11 void lock(lock_t *lock) {
12     int myturn = FetchAndAdd(&lock->ticket);
13     while (lock->turn != myturn)
14         ; // spin
15 }
16
17 void unlock(lock_t *lock) {
18     lock->turn = lock->turn + 1;
19 }
```

Figure 28.7: Ticket Locks

5. Exercises

See the book for exercises using [x86.py](#)

```
$ cat flags
.var flag
.var count

.main
.top

.acquire
mov flag, %ax      # get flag
test $0, %ax        # if we get 0 back: lock is free!
jne .acquire        # if not, try again
mov $1, flag         # store 1 into flag

# critical section
mov count, %ax      # get the value at the address
add $1, %ax          # increment it
mov %ax, count       # store it back

# release lock
mov $0, flag         # clear the flag now

# see if we're still looping
sub $1, %bx
test $0, %bx
jgt .top

halt
```

6. Q2

```
$ python ./x86.py -p flag.s -R ax,bx -a bx=2 -M flag,count -c
```

flag	count	ax	bx	Thread 0	Thread 1
0	0	0	2		
0	0	0	2	1000 mov flag, %ax	
0	0	0	2	1001 test \$0, %ax	
0	0	0	2	1002 jne .acquire	
1	0	0	2	1003 mov \$1, flag	
1	0	0	2	1004 mov count, %ax	
1	0	1	2	1005 add \$1, %ax	
1	1	1	2	1006 mov %ax, count	
0	1	1	2	1007 mov \$0, flag	
0	1	1	1	1008 sub \$1, %bx	
0	1	1	1	1009 test \$0, %bx	
0	1	1	1	1010 jgt .top	
0	1	0	1	1000 mov flag, %ax	
0	1	0	1	1001 test \$0, %ax	
0	1	0	1	1002 jne .acquire	
1	1	0	1	1003 mov \$1, flag	
1	1	1	1	1004 mov count, %ax	
1	1	2	1	1005 add \$1, %ax	
1	2	2	1	1006 mov %ax, count	
0	2	2	1	1007 mov \$0, flag	
0	2	2	0	1008 sub \$1, %bx	
0	2	2	0	1009 test \$0, %bx	
0	2	2	0	1010 jgt .top	
0	2	2	0	1011 halt	
0	2	0	2	----- Halt;Switch -----	----- Halt;Switch -----
0	2	0	2	1000 mov flag, %ax	
0	2	0	2	1001 test \$0, %ax	
0	2	0	2	1002 jne .acquire	
1	2	0	2	1003 mov \$1, flag	
1	2	2	2	1004 mov count, %ax	
1	2	3	2	1005 add \$1, %ax	
1	3	3	2	1006 mov %ax, count	
0	3	3	2	1007 mov \$0, flag	
0	3	3	1	1008 sub \$1, %bx	
0	3	3	1	1009 test \$0, %bx	
0	3	3	1	1010 jgt .top	
0	3	0	1	1000 mov flag, %ax	
0	3	0	1	1001 test \$0, %ax	
0	3	0	1	1002 jne .acquire	
1	3	0	1	1003 mov \$1, flag	
1	3	3	1	1004 mov count, %ax	
1	3	4	1	1005 add \$1, %ax	
1	4	4	1	1006 mov %ax, count	
0	4	4	1	1007 mov \$0, flag	
0	4	4	0	1008 sub \$1, %bx	
0	4	4	0	1009 test \$0, %bx	
0	4	4	0	1010 jgt .top	
0	4	4	0	1011 halt	

7. Q4

\$ python ./x86.py -p flag.s -R ax,bx -a bx=2 -M flag,count -c -i 6				flag	count	ax	bx	Thread 0	Thread 1
flag	count	ax	bx	Thread 0		Thread 1			
0	0	0	2					1001 test \$0, %ax	
0	0	0	2	1000 mov flag, %ax		1	1	1002 jne .acquire	
0	0	0	2	1001 test \$0, %ax		1	1	1003 mov \$1, flag	
0	0	0	2	1002 jne .acquire		1	1	1004 mov count, %ax	
1	0	0	2	1003 mov \$1, flag		1	2	1005 add \$1, %ax	
1	0	0	2	1004 mov count, %ax		1	2	1006 mov %ax, count	
1	0	1	2	1005 add \$1, %ax		0	2	----- Interrupt -----	----- Interrupt -----
1	0	0	2	----- Interrupt -----		0	2	1006 mov %ax, count	
1	0	1	2		1000 mov flag, %ax	0	2	1007 mov \$0, flag	
1	0	1	2		1001 test \$0, %ax	0	2	1008 sub \$1, %bx	
1	0	1	2		1002 jne .acquire	0	2	1009 test \$0, %bx	
1	0	1	2		1000 mov flag, %ax	0	2	1010 jgt .top	
1	0	1	2		1001 test \$0, %ax	0	2	1000 mov flag, %ax	
1	0	1	2		1002 jne .acquire	0	2	----- Interrupt -----	----- Interrupt -----
1	0	1	2		1000 mov flag, %ax	0	2	1007 mov \$0, flag	
1	0	1	2		1001 test \$0, %ax	0	2	1008 sub \$1, %bx	
1	0	1	2		1002 jne .acquire	0	2	1009 test \$0, %bx	
1	0	1	2	----- Interrupt -----	----- Interrupt -----	0	2	1010 jgt .top	
1	1	1	2	1006 mov %ax, count		0	2	1011 halt	
0	1	1	2	1007 mov \$0, flag		0	2	----- Halt;Switch -----	----- Halt;Switch -----
0	1	1	1	1008 sub \$1, %bx		0	2	1001 test \$0, %ax	
0	1	1	1	1009 test \$0, %bx		0	2	1010 jgt .top	
0	1	1	1	1010 jgt .top		0	2	----- Interrupt -----	----- Interrupt -----
0	1	0	1	1000 mov flag, %ax		0	2	1002 jne .acquire	
0	1	1	2	----- Interrupt -----	----- Interrupt -----	1	2	1003 mov \$1, flag	
0	1	0	2		1000 mov flag, %ax	1	2	1004 mov count, %ax	
0	1	0	2		1001 test \$0, %ax	1	2	1005 add \$1, %ax	
0	1	0	2		1002 jne .acquire	1	3	1006 mov %ax, count	
1	1	0	2		1003 mov \$1, flag	0	3	1007 mov \$0, flag	
1	1	1	2		1004 mov count, %ax	0	3	----- Interrupt -----	----- Interrupt -----
1	1	2	2		1005 add \$1, %ax	0	3	1008 sub \$1, %bx	
1	1	0	1	----- Interrupt -----	----- Interrupt -----	0	3	1009 test \$0, %bx	
						0	3	1010 jgt .top	
						0	3	1011 halt	

8. Q5

```
$ cat test-and-set.s
.var mutex
.var count

.main
.top

.acquire
mov $1, %ax
xchg %ax, mutex      # atomic swap of 1 and mutex
test $0, %ax          # if we get 0 back: lock is free!
jne .acquire          # if not, try again

# critical section
mov count, %ax        # get the value at the address
add $1, %ax            # increment it
mov %ax, count         # store it back

# release lock
mov $0, mutex

# see if we're still looping
sub $1, %bx
test $0, %bx
jgt .top

halt
```

9. Q6

```
$ python ./x86.py -p test-and-set.s -R ax,bx -a bx=2 -M mutex,count -c -i 6
```

mutex count	ax	bx	Thread 0	Thread 1	mutex count	ax	bx	Thread 0	Thread 1
0 0	0 2				1 1	1 2			1004 mov count, %ax
0 0	1 2	1000 mov \$1, %ax			1 1	2 2			1005 add \$1, %ax
1 0	0 2	1001 xchg %ax, mutex			0 2	2 2			1006 mov %ax, count
1 0	0 2	1002 test \$0, %ax			0 2	2 1			1007 mov \$0, mutex
1 0	0 2	1003 jne .acquire			0 2	2 1	----- Interrupt -----	----- Interrupt -----	1008 sub \$1, %bx
1 0	0 2	1004 mov count, %ax			0 2	1 1	1003 jne .acquire		1009 test \$0, %bx
1 0	1 2	1005 add \$1, %ax			0 2	1 1	1000 mov \$1, %ax		
1 0	0 2	----- Interrupt -----	----- Interrupt -----		1 2	0 1	1001 xchg %ax, mutex		
1 0	1 2		1000 mov \$1, %ax		1 2	0 1	1002 test \$0, %ax		
1 0	1 2		1001 xchg %ax, mutex		1 2	0 1	1003 jne .acquire		
1 0	1 2		1002 test \$0, %ax		1 2	2 1	1004 mov count, %ax		
1 0	1 2		1003 jne .acquire		1 2	2 1	----- Interrupt -----	----- Interrupt -----	
1 0	1 2		1000 mov \$1, %ax		1 2	2 1			1010 jgt .top
1 0	1 2		1001 xchg %ax, mutex		1 2	1 1			1000 mov \$1, %ax
1 0	1 2	----- Interrupt -----	----- Interrupt -----		1 2	1 1			1001 xchg %ax, mutex
1 1	1 2	1006 mov %ax, count			1 2	1 1			1002 test \$0, %ax
0 1	1 2	1007 mov \$0, mutex			1 2	1 1			1003 jne .acquire
0 1	1 1	1008 sub \$1, %bx			1 2	1 1			1000 mov \$1, %ax
0 1	1 1	1009 test \$0, %bx			1 2	2 1	----- Interrupt -----	----- Interrupt -----	
0 1	1 1	1010 jgt .top			1 2	3 1	1005 add \$1, %ax		
0 1	1 1	1000 mov \$1, %ax			1 3	3 1	1006 mov %ax, count		
0 1	1 2	----- Interrupt -----	----- Interrupt -----		0 3	3 1	1007 mov \$0, mutex		
0 1	1 2		1002 test \$0, %ax		0 3	3 0	1008 sub \$1, %bx		
0 1	1 2		1003 jne .acquire		0 3	3 0	1009 test \$0, %bx		
0 1	1 2		1000 mov \$1, %ax		0 3	3 0	1010 jgt .top		
1 1	0 2		1001 xchg %ax, mutex		0 3	1 1	----- Interrupt -----	----- Interrupt -----	
1 1	0 2		1002 test \$0, %ax		1 3	0 1			1001 xchg %ax, mutex
1 1	0 2		1003 jne .acquire		1 3	0 1			1002 test \$0, %ax
1 1	1 1	----- Interrupt -----	----- Interrupt -----		1 3	0 1			1003 jne .acquire
1 1	1 1	1001 xchg %ax, mutex			1 3	3 1			1004 mov count, %ax
1 1	1 1	1002 test \$0, %ax			1 3	4 1			1005 add \$1, %ax
1 1	1 1	1003 jne .acquire			1 4	4 1			1006 mov %ax, count
1 1	1 1	1000 mov \$1, %ax			1 4	3 0	----- Interrupt -----	----- Interrupt -----	
1 1	1 1	1001 xchg %ax, mutex			1 4	3 0	1011 halt		
1 1	1 1	1002 test \$0, %ax			1 4	4 1	----- Halt;Switch -----	----- Halt;Switch -----	
1 1	0 2	----- Interrupt -----	----- Interrupt -----		0 4	4 1			1007 mov \$0, mutex
					0 4	4 0			1008 sub \$1, %bx
					0 4	4 0			1009 test \$0, %bx
					0 4	4 0			1010 jgt .top
					0 4	4 0			1011 halt